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Unsteady flux correction method for solving aeroacoustic problems on unstructured meshes

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Schemes on unstructured meshes

Schemes for solving Euler equations

Very high (3rd and higher) order methods

- Discontinuous Galerkin
- FV polynomial-based
- SD, SV, etc.
- **Very good accuracy for smooth solutions**
- Enforcing monotonicity leads to loss of accuracy
- Very expensive, especially for problems with discontinuities

2nd order Godunov-type methods

- cell-centered schemes
- vertex-centered (edge-based) schemes
- **Cheap**
- **Easy to realize**
- Just 2nd order

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- **Constructing new limiters, etc.**

2nd order Godunov-type methods

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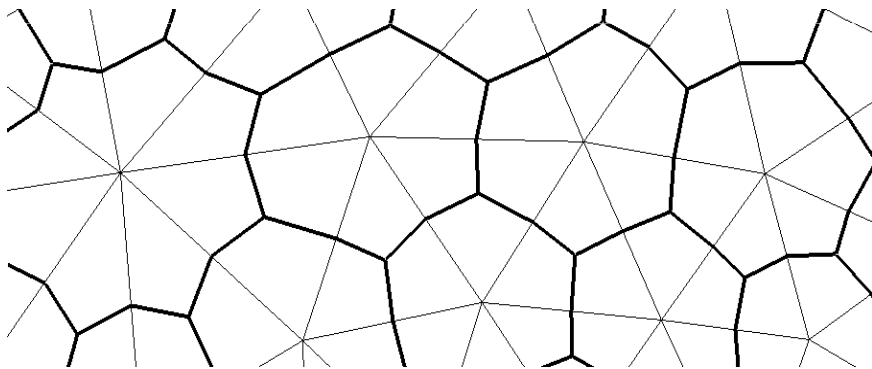
- **Cheap**
- **Easy to realize**
- Just 2nd order

- **Increasing accuracy within 2nd order of accuracy**

«Linear» scheme of T. Barth

- 1980th: idea of equipping P1-Galerkin method with artificial dissipation
- Roe [1] found a finite-volume interpretation of P1-Galerkin method
- Barth [2] used this result to construct a 2nd order scheme consisting of linear reconstruction of variables and Godunov-type Riemann solver
- Now «Linear» scheme **is an ancestor of most vertex-centered schemes**

$$[\nabla \cdot \mathbf{F}]|_i = \frac{1}{V_i} \sum_{j \in N(i)} \left(\frac{\mathbf{F}(Q_i) + \mathbf{F}(Q_j)}{2} - \frac{1}{2} \left(\frac{d\mathbf{F}}{dQ}(\bar{Q}_{ij}) \right) (Q_{ij}^+ - Q_{ij}^-) \right) \cdot \mathbf{n}_{ij}$$



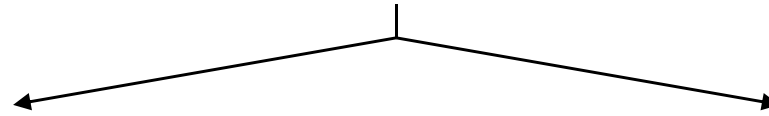
Barycentric control volumes define V_i and \mathbf{n}_{ij}

[1] P. L. Roe, “Error estimates for cell-vertex solutions of the compressible Euler equations”, ICASE report No. 87-6 (1987)

[2] T. J. Barth, “A 3-D upwind Euler solver for unstructured meshes”, AIAA Paper No. 91-1548 (1991)

Increasing accuracy of 2nd order schemes

Two main approaches based on «Linear» scheme of T. Barth



Quasi-1D approach

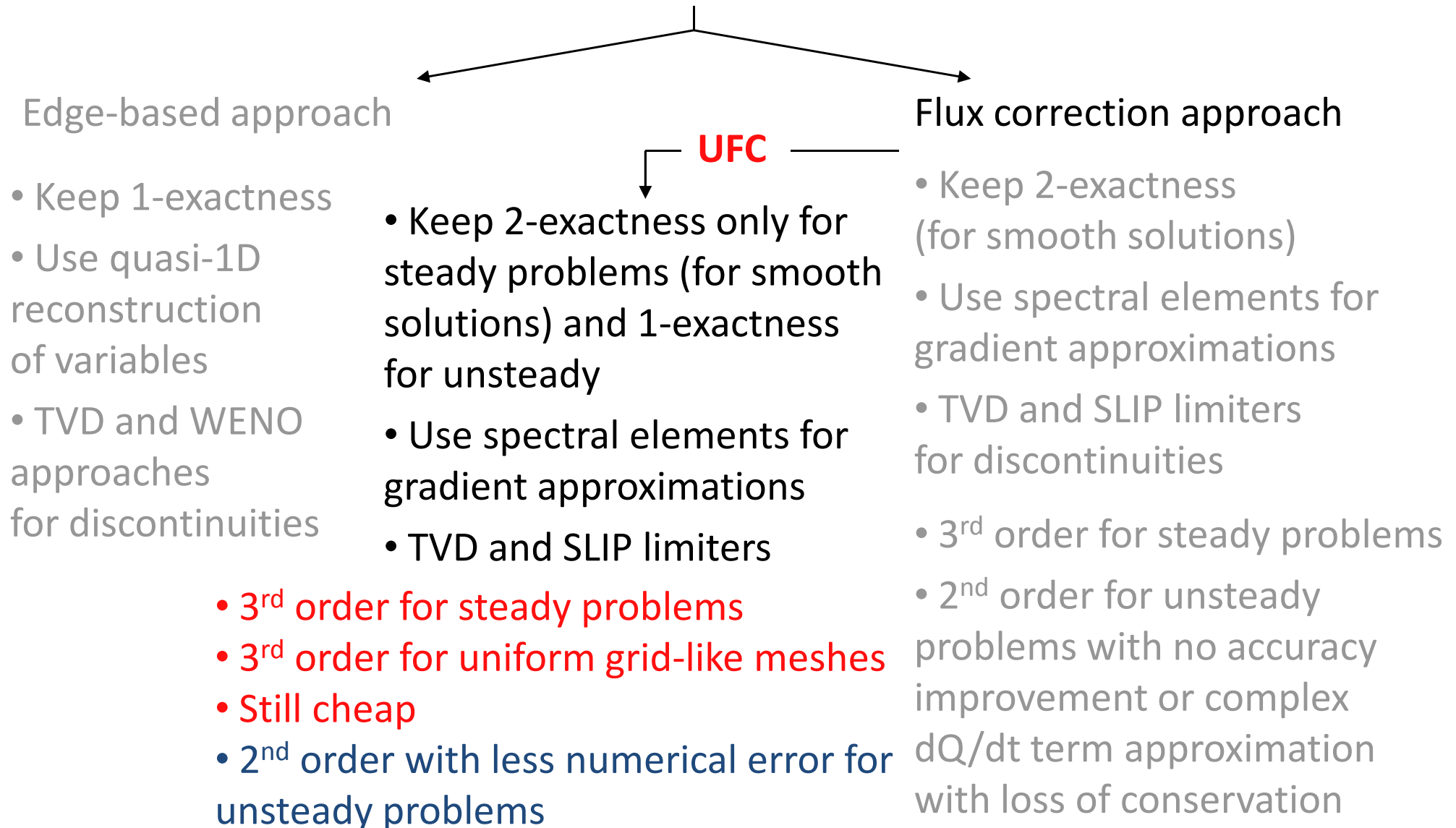
- Keeps 1-exactness
- Uses quasi-1D reconstruction of variables
- TVD and WENO techniques for discontinuities
- Reduces to 5th order FD scheme for uniform grid-like meshes
- Cheap
- 2nd order for unstructured meshes but better accuracy than «Linear» scheme

Flux correction approach

- Makes 2-exactness (for smooth solutions)
- Uses spectral elements for gradient approximations
- TVD and SLIP limiters for discontinuities
- 3rd order for steady problems
- 2nd order for unsteady problems with no accuracy improvement or complex dQ/dt term approximation with loss of conservation

Increasing accuracy of 2nd order schemes

Two main approaches based on «Linear» scheme of T. Barth



Desirable properties of Edge-based schemes

- 1 - conservation
- 2 - exactness on linear functions (1-exactness)
- 3 – high (3rd-5th) order of accuracy on uniform structured meshes
- 4 - 3rd order of accuracy for steady problems on arbitrary meshes
- 5 - 3rd order of accuracy for unsteady problems on arbitrary meshes
- 6 - significantly cheaper than very high order scheme

	1	2	3	4	5	6
Linear scheme	+	+	-	-	-	+
EBR, SEBR, MEV, NLV6, LV6, ..	+	+	+	-	-	+
UFC	+	+	+	+	-	+
steady FC	+	+	-	+	-	+
FC modifications of Nishikawa, Pincock	-	+	+	+	+	-

Edge-based vertex-centered schemes

$$\frac{\partial \mathbf{Q}}{\partial t} + \nabla \cdot \mathcal{F}(\mathbf{Q}) = 0$$

Euler Eqs

$$\mathbf{Q} = (\rho, \rho \mathbf{u}, E)^T$$

$$\mathcal{F} = \begin{pmatrix} \rho \mathbf{u} \\ \rho \mathbf{u} \mathbf{u} + p \mathbf{I} \\ (E + p) \mathbf{u} \end{pmatrix}$$

Linearised Euler Eqs

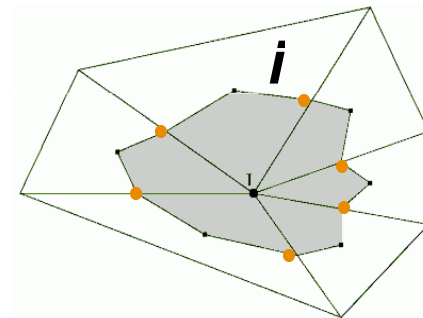
$$\mathbf{Q} = (\rho', \mathbf{u}', p' / (\gamma - 1))^T$$

$$\mathcal{F} = \begin{pmatrix} \mathbf{u}' \\ p' \mathbf{I} \\ \mathbf{u}' / (\gamma - 1) \end{pmatrix}$$

$$\left(\frac{d\mathbf{Q}}{dt} \right)_i = -\frac{1}{V_i} \sum_{j \in N_1(i)} \mathbf{h}_{ij}, \quad \mathbf{h}_{ij} = -\mathbf{h}_{ji}$$

$$\mathbf{h}_{ij} = \mathcal{F}_{ij} \cdot \mathbf{n}_{ij} \quad \mathbf{n}_{ij} = \int_{\partial C_{ij}} \mathbf{n} ds$$

\mathcal{F}_{ij} evaluated at edge ij midpoint



Flux Correction (FC) Scheme

$$\frac{\partial u}{\partial t} + \mathbf{a} \cdot \nabla u = 0$$

$$\frac{du_i}{dt} + [\mathbf{a} \cdot \nabla u]_i^{FC} = 0$$

$$[\nabla u(x)]_i^{FC} = \frac{1}{V_i} \sum_{j \in N_1(i)} \mathbf{n}_{ij} u_{ij}$$

$$u_{ij} = \begin{cases} u_{ij}^{(i)}, & \mathbf{a}_{ij} \cdot \mathbf{n}_{ij} \geq 0 \\ u_{ij}^{(j)}, & \mathbf{a}_{ij} \cdot \mathbf{n}_{ij} < 0 \end{cases} \quad \begin{aligned} u_{ij}^{(i)} &= u_i + \frac{1}{2} (\mathbf{r}_j - \mathbf{r}_i) \cdot \nabla u(\mathbf{r}_i) \\ u_{ij}^{(j)} &= u_j + \frac{1}{2} (\mathbf{r}_i - \mathbf{r}_j) \cdot \nabla u(\mathbf{r}_j) \end{aligned}$$

$\nabla u(\mathbf{r}_i), \nabla u(\mathbf{r}_j)$ are calculated accurately enough

Katz A., and Sankaran V., "An Efficient Correction Method to Obtain a Formally Third-Order Accurate Flow Solver for Node-Centered Unstructured Grids," *Journal of Scientific Computing*, Vol. 51, 2012

Construction of the UFC scheme

Original steady FC scheme: $\frac{du}{dt} + [\mathbf{a} \cdot \nabla u]^{FC} = 0$ – 2nd order of accuracy

UFC scheme on TS meshes: $\frac{du}{dt} + \hat{U} [\mathbf{a} \cdot \nabla u]^{FC} = 0$ – 3rd order of accuracy

$$\hat{u}_{ik} = \begin{cases} C/12, & k \in N_1(i) \\ 1 - C|N_1(i)|/12, & k = i \\ 0 & otherwise \end{cases} \quad C = \begin{cases} 1, & 1D \\ 1/2, & 2D \\ 1/4, & 3D \end{cases}$$

UFC scheme on arbitrary simplicial mesh:

1. Scheme must be conservative
2. Scheme must be 1-exact
3. U must coincide with \hat{U} on TS-meshes

$$\frac{du}{dt} + U [\mathbf{a} \cdot \nabla u]^{FC} = 0$$

$$u_{ik} = \begin{cases} \frac{C}{12} \frac{v_i + v_k}{2v_i}, & k \in N_1(i) \\ 1 - \frac{C}{12} \sum_{k \in N_1(i)} \frac{v_i + v_k}{2v_i}, & k = i \\ 0 & otherwise \end{cases}$$

2D and 3D numerical results

Linearized Euler equations, Gaussian pulse evolution

$$\bar{\rho} = 1 \quad \bar{\mathbf{u}} = 0 \quad \bar{p} = 1/\gamma$$

$$\rho'|_{t=0} = p'|_{t=0} = A \exp\left(-\ln 2 \left(\frac{\mathbf{r}}{b}\right)^2\right) \quad A = \begin{cases} 1, & 2\text{D} \\ 1/2, & 3\text{D} \end{cases} \quad b = 6$$

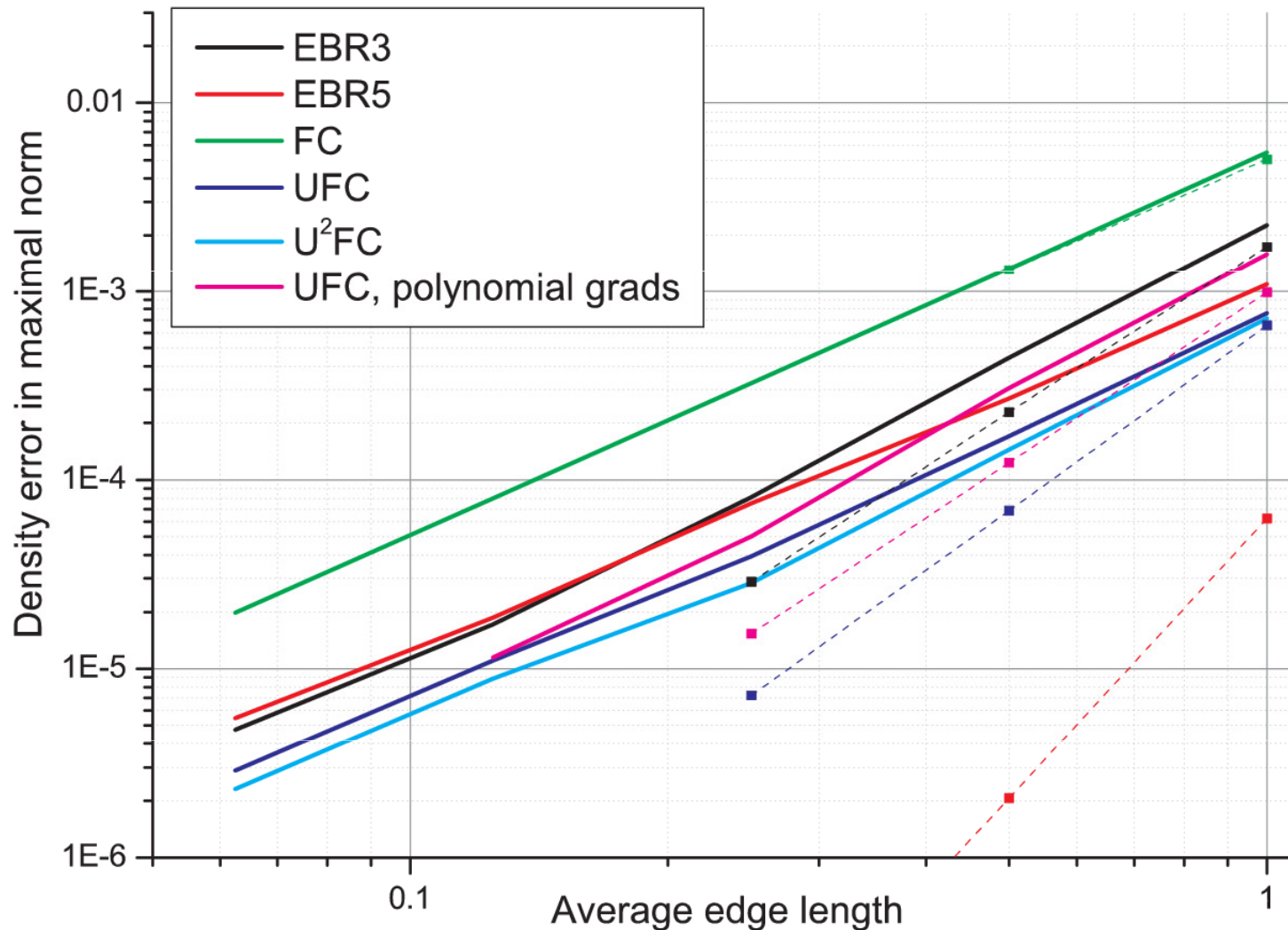
$$T = 40$$

Scheme		EBR3	EBR5	Steady FC	UFC
Maximal norm	h=1	1.73289e-003	6.24980e-005	5.03122e-003	6.57931e-004
	h=0.5	2.28420e-004	2.05613e-006	1.30860e-003	6.86734e-005
	h=0.25	2.89376e-005	7.16193e-008	3.28580e-004	7.22010e-006
	num. order	2.98	4.84	2.00	3.25
Integral norm	h=1	2.77561e-004	9.39937e-006	7.23611e-004	5.43120e-005
	h=0.5	3.55518e-005	3.01253e-007	1.85495e-004	5.04358e-006
	h=0.25	4.45939e-006	1.13177e-008	4.67779e-005	6.59735e-007
	num. order	3.00	4.73	1.99	2.93

Triangular
TS-meshes

Maximal norm	h=1	2.2576e-003	1.08382e-003	5.47836e-003	7.63247e-4
	h=0.5	4.42802e-4	2.69707e-4	1.32e-3	1.70302e-4
	h=0.25	8.08705e-5	7.52786e-5	3.2483e-4	3.94256e-5
	h=0.125	1.72135e-5	1.85921e-5	7.98531e-5	1.10177e-5
	h=0.0625	4.76772e-6	5.46002e-6	1.97773e-5	2.87777e-6
num. order	1.85	1.76	2.01	1.94	
Integral norm	h=1	2.78876e-004	7.10360e-005	7.50898e-004	6.00207e-005
	h=0.5	3.10223e-005	1.24319e-005	1.79015e-004	6.97642e-006
	h=0.25	4.33573e-06	2.91023e-06	4.51444e-05	1.53294e-06
	h=0.125	6.89182e-07	7.42516e-07	1.13290e-05	3.95812e-07
	h=0.0625	1.39072e-07	1.85712e-07	2.81990e-06	9.91140e-08
num. order	2.31	2.00	2.01	2.00	

Quasi-uniform
unstructured
triangular
meshes



Solution convergence on triangular meshes:
 unstructured mesh versus TS-mesh (of the same color in dash)

Scheme		EBR3	EBR5	Steady FC	UFC
Maximal norm	h=1	6.71e-3	7.41e-4	1.15e-2	4.10e-3
	h=1/2	9.71e-4	2.63e-5	2.75e-3	5.14e-4
	num. order	2.79	4.84	2.06	3.00
Integral norm	h=1	1.66e-3	1.59e-4	3.12e-3	9.78e-4
	h=1/2	2.31e-4	7.71e-6	8.03e-4	1.21e-4
	num. order	2.85	4.88	1.96	3.01
	theor. order	3	5	2	3

Tetrahedral
TS-meshes

Scheme		EBR3	EBR5	Steady FC	UFC
Maximal norm	h=1	4.79e-3	1.82e-3	1.39e-2	2.82e-3
	h=1/2	6.54e-4	4.36e-4	3.21e-3	3.51e-4
	h=1/4	1.04e-4	1.09e-4	7.68e-4	5.99e-5
	num. order	2.65	2.41	2.00	2.55
Integral norm	h=1	7.23e-4	2.50e-4	2.35e-3	4.45e-4
	h=1/2	9.70e-5	5.15e-5	6.02e-4	5.70e-5
	h=1/4	1.37e-5	1.24e-5	1.51e-4	8.22e-6
	num. order	2.94	2.03	2.01	2.79
	theor. order	2	2	2	2

Quasi-uniform
unstructured
tetrahedral
meshes

Conclusion

We have presented the **Unsteady flux correction (UFC)** method.
At this point we have developed the scheme for smooth solution only.

For linear case the UFC scheme is:

- conservative;
- of second order on arbitrary meshes;
- of third order on uniform grid-like meshes;
- of third order on steady problems;
- as cheap as the original steady FC method.

FC scheme is easy to realize and need no geometry preprocessing so it is well suitable for solving problems on deforming meshes.